References

Aracil J and Gordillo F 2004 Describing function method for stability analysis of PD and PI fuzzy controllers. *Fuzzy Sets and Systems* **143**, 233–249.

Assilian S and Mamdani E 1974a Learning control algorithms in real dynamic systems. *Proc. Fourth Int. Conf. On Digital Computer Applications to Process Control, Zürich*, pp. 13–20 IFAC/IFIP. Springer.

Assilian S and Mamdani EH 1974b An experiment in linguistic synthesis with a fuzzy logic controller. *Int. J. Man Machine Studies* 7(1), 1–13.

Åström KJ and Hägglund T 2006 *Advanced PID Control*. Instrumentation, Systems, and Automation Society (ISA), ISA, 67 Alexander Drive, PO Box 12277, Research Triangle Park, North Carolina 27709, USA.

Åström KJ and Wittenmark B 1984 Computer controlled systems - theory and design. Prentice-Hall.

Åström KJ and Wittenmark B 1995 Adaptive Control 2nd edn. Addison-Wesley.

Atherton D 2011 An Introduction to Nonlinearity in Control Systems. Ventus Publishing ApS, Available from: bookboon.com [cited 17 Feb 2013].

Atherton DP 1975 Nonlinear Control Engineering unabridged edn. Van Nostrand Reinhold Company.

Atherton DP 1982 Nonlinear Control Engineering student edn. Van Nostrand Reinhold Company.

Babuška R 1998 Fuzzy Modeling For Control. Kluwer Academic Publishers.

Babuška R 1999 An overview of fuzzy modelling and model-based fuzzy control In *Fuzzy Logic Control: Advances in Applications* (ed. Verbruggen HB and Babuška R) Robotics and Intelligent Systems – Vol 23 World Scientific pp. 3–35. ISBN 981-02-3825-8.

Bennett S 1993 Development of the PID controller. IEEE Control Systems 13(5), 58-65.

Bequette B 2003 Process Control: Modeling, Design, and Simulation PTR. Prentice Hall.

Bezdek J and Pal SK 1992 Fuzzy models for pattern recognition. IEEE Press, New York. (Selected reprints).

Bhatti A, Spurgeon, SK DR, and Edwards C 1999 Sliding mode configurations for automotive engine control. *International Journal of Adaptive Control and Signal Processing* 13, 49–69.

Braae M and Rutherford D 1979a Selection of parameters for a fuzzy logic controller. Fuzzy Sets and Systems 2, 185–199.

Braae M and Rutherford D 1979b Theoretical and linguistic aspects of the fuzzy logic controller. *Automatica* 15, 553–577.

Cohen G and Coon G 1953 Theoretical consideration of retarded control. *Trans. of American society of Mechanical Engineers*, ASME 75, 827–834.

Cominos P and Munro N 2002 PID controllers: recent tuning methods and design to specification. *IEE Proceedings – Control Theory And Applications* **149**(1), 46–53.

Cuesta F, Gordillo F, Aracil J, and Ollero A 1999 Stability analysis of nonlinear multivariable Takagi-Sugeno fuzzy control systems. *IEEE Transactions on Fuzzy Systems* **7**(5), 508–520.

DiStefano J, Stubberud A, and Williams I 1995 Schaum's Outline of Theory and Problems of Feedback and Control Systems Schaum's Outline Series 2nd edn. McGraw-Hill.

Driankov D, Hellendoorn H, and Reinfrank M 1996 An introduction to fuzzy control 2nd edn. Springer-Verlag.

Duda RO, Hart PE, and Stork DG 2001 Pattern Classification 2. edn. Wiley-Interscience.

316 References

Edwards C and Spurgeon SK 1998 Sliding Mode Control: Theory and Applications Systems and Control Book Series.

Taylor & Francis.

Farinwata SS, Filev D, and Langari R (eds.) 2000 Fuzzy Control: Synthesis And Analysis. Wiley.

Franklin GF, Powell JD, and Emami-Naeini A 1991 *Feedback Control of Dynamic Systems* Electrical and Computer Engineering: Control Engineering 2nd edn. Addison-Wesley.

Franksen OI 1979 Group representation of finite polyvalent logic In *Proceedings 7th IFAC Triennial World Congress*, *Helsinki* (ed. Niemi A) International Federation of Automatic Control, IFAC. Pergamon Press.

Fukami S, Mizumoto M, and Tanaka K 1980 Some considerations of fuzzy conditional inference. *Fuzzy Sets and Systems* **4**, 243–273.

Gelb A and Vander Velde WE 1968 *Multiple-Input Describing Functions and Nonlinear System Design*. McGraw-Hill, Also available from: http://ocw.mit.edu [cited 17 Feb 2013].

Gordillo F, Aracil J, and Álamo T 1997 Determining limit cycles in fuzzy control systems *Proceedings of 6th International Fuzzy Systems Conference*, vol. 1, pp. 193–198. IEEE.

Gupta MM and Sinha NK (eds.) 1996 Intelligent Control Systems: Theory and practice. IEEE Press.

Guzman J, Åström K, Dormido S, Hägglund T, Berenguel M, and Piguet Y 2008 Interactive learning modules for PID control. *IEEE Control Systems* **28**(5), 118–134.

Gyöngy IJ and Clarke DW 2006 On the automatic tuning and adaptation of PID controllers. *Control Engineering Practice* **14**, 149–163.

Hájek P 1998 Metamathematics of Fuzzy Logic Trends in Logic. Kluwer.

Hametner C and Jakubek S 2013 Local model network identification for online engine modelling. *Information Sciences* 220, 210–225.

Haykin S 2009 Neural Networks and Learning Machines 3rd edn. Pearson Education.

Hendricks E and Sorenson S 1990 Mean value modelling of spark ignition engines. SAE technical paper 900616.

Holmblad LP and Østergaard JJ 1982 Control of a cement kiln by fuzzy logic In *Fuzzy Information and Decision Processes* (ed. Gupta and Sanchez) North-Holland Amsterdam pp. 389–399. (Reprint in: FLS Review No 67, FLS Automation A/S, Høffdingsvej 77, DK-2500 Valby, Copenhagen, Denmark).

Holmblad LP and Østergaard JJ 1995 The FLS application of fuzzy logic. Fuzzy Sets and Systems 70, 135-146.

IEC 2000 Programmable controllers – part 7: Fuzzy control programming. Technical Report IEC 61131, International Electrotechnical Ccommission (IEC). Draft available from http://www.fuzzytech.com/binaries/ieccd1.pdf [cited on 17 Feb 2013].

Isaksson A and Hägglund T (eds.) 2002 Special section on PID Control vol. 149.

Jakubek S, Hametner C, and Keuth N 2008 Total least squares in fuzzy system identification: An application to an industrial engine. *Engineering Applications of Artificial Intelligence* **21**, 1277–1288.

Jang JSR and Sun CT 1995 Neuro-fuzzy modeling and control In Proceedings of the IEEE (ed. 3), 83, 378-406.

Jang JSR, Sun CT, and Mizutani E 1997 Neuro-Fuzzy and Soft Computing MATLAB Curriculum Series. Prentice Hall.

Jantzen J 1995 Array approach to fuzzy logic. Fuzzy Sets and Systems 70, 359-370.

Jantzen J 2003 Internet learning in control: A fuzzy control course In *Prepr. ACE 2003, The 6th IFAC Symposium on Advances in Control Education* (ed. Lindfors J), pp. 27–33. IFAC.

Jantzen J, Verbruggen H, and Østergaard JJ 1999 Fuzzy control in the process industry: Common practice and challenging perspectives In *Practical Applications of Fuzzy Technologies* (ed. Zimmermann HJ) Dubois and Prade (Eds), The Handbooks of Fuzzy Sets Series Kluwer chapter 1, pp. 3–56.

Jespersen T 1981 Self-organizing fuzzy logic control of a pH-neutralisation process. Technical Report 8102, Electric Power Eng. Dept., Technical University of Denmark.

Jørgensen V 1974 A ball-balancing system for demonstration of basic concepts in the state-space control theory. *Int. J. Elect. Enging Educ.* **11**, 367–376.

Kickert W and Mamdani E 1978 Analysis of a fuzzy logic controller. Fuzzy Sets and Systems 1, 29-44.

Kickert WJM and Van Nauta Lemke HR 1976 Application of a fuzzy controller in a warm water plant. *Automatica* **12**(4), 301–308.

Kiszka JB, Kochanska ME, and Sliwinska DS 1985 The influence of some fuzzy implication operators on the accuracy of a fuzzy model. *Fuzzy Sets and Systems* **15**, (Part1) 111–128; (Part 2) 223–240.

Kosko B 1992 Neural Networks and Fuzzy Systems. A Dynamical Systems Approach to Machine Intelligence.

Prentice-Hall.

Larsen PM 1981 Industrial applications of fuzzy logic control In *Fuzzy Reasoning and its Applications* (ed. Mamdani EH and Gaines BR) Academic Press London pp. 335–342.

Lee CC 1990 Fuzzy logic in control systems: Fuzzy logic controller. *IEEE Trans. Systems, Man & Cybernetics* **20**(2), 404–435.

Lewis R 1990 Practical Digital Image Processing Ellis Horwood Series in Digital and Signal Processing. Ellis Horwood Ltd, New York, etc.

Li HX and Gatland HB 1995 A new methodology for designing a fuzzy logic controller. *IEEE Trans. Systems, Man & Cybernetics* **25**(3), 505–512.

Lin CT and Lee CSG 1996 Neural Fuzzy Systems: A Neuro-Fuzzy Synergism to Intelligent Systems. Prentice Hall PTR.

Luenberger DG 1969 Optimization by Vector Space Methods Series in Decision and Control. Wiley.

Maclay D and Dorey R 1995 A controller and design implementation environment for the idle speed control of an internal combustion engine. *IEE Colloquium Digest* 14, 1–3.

Mamdani E and Baaklini N 1975 Prescriptive method for deriving control policy in a fuzzy-logic controller. *Electronics Letters* **11**(25/26), 625–626.

Mamdani EH 1977 Application of fuzzy logic to approximate reasoning using linguistic synthesis. *IEEE Transactions on Computers* C-26(12), 1182–1191.

MathWorks 2012 Fuzzy Logic Toolbox for Use with Matlab: User's Guide. online edn The MathWorks Inc. Available from www.mathworks.se [cited 22 Jul 2012].

Michels K, Klawonn F, Kruse R, and Nürnberger A 2006 Fuzzy Control: Fundamentals, Stability and Design of Fuzzy Controllers. Springer.

Mizumoto M 1992 Realization of PID controls by fuzzy control methods *First Int. Conf. on Fuzzy Systems*, pp. 709–715 The Institute of Electrical and Electronics Engineers, Inc, San Diego.

Mizumoto M 1995 Realization of PID controls by fuzzy control methods. Fuzzy Sets and Systems 70, 171-182.

Mizumoto M, Fukami S, and Tanaka K 1979 Some methods of fuzzy reasoning In *Advances in Fuzzy Set Theory Applications* (ed. Gupta, Ragade, and Yager) North-Holland, New York.

Møller G 1986 A logic programming tool for qualitative system design. APL Quote Quad (APL86 conference proceedings) 16(4), 266–271.

Møller GL 1998 On the Technology of Array-Based Logic PhD thesis Technical University of Denmark, Electric Power Engineering Dept., DK-2800 Lyngby, Denmark (2nd ed.).

Murakami S, Takemoto F, Fulimura H, and Ide E 1989 Weld-line tracking control of arc welding robot using fuzzy logic controller. *Fuzzy Sets and Systems* **32**(2), 221–237.

Nauck D, Klawonn F, and Kruse R 1997 Foundations of Neuro-Fuzzy Systems. John Wiley and Sons.

Nelles O 2001 Nonlinear System Identification. Springer-Verlag.

Nguyen HT and Walker EA 2000 A first course in fuzzy logic 2nd edn. Chapman & Hall, New York.

Nise N 1995 Control Systems Engineering 2nd edn. Benjamin/Cummings.

Østergaard JJ 1977 Fuzzy logic control of a heat exchanger system In *Fuzzy Automata and Decision Processes* (ed. Gupta MM, Saridis GN, and Gaines BR) North-Holland Amsterdam pp. 285–320.

Østergaard JJ 1990 Fuzzy II: The new generation of high level kiln control. Zement Kalk Gips (Cement-Lime-Gypsum) 43(11), 539–541.

Østergaard JJ 1996 High level control of industrial processes In *Proc. TOOLMET* '96 (ed. Yliniemi L and Juuso E), pp. 1–12. University of Oulu, Control Engineering Laboratory, Linnanmaa, FIN-90570 Oulu, Finland.

Palm R, Driankov D, and Hellendoorn H 1997 Model Based Fuzzy Control. Springer.

Passino KM and Yurkovich S 1998 Fuzzy Control. Addison Wesley Longman, Inc.

Pedrycz W 1993 Fuzzy control and fuzzy systems 2nd edn. Wiley and Sons.

Precup RE and Hellendoorn H 2011 A survey on industrial applications of fuzzy control. *Computers in Industry* **62**, 213–226.

Procyk TJ and Mamdani EH 1979 A linguistic self-organizing process controller. Automatica 15, 15–30.

Qiao W and Mizumoto M 1996 PID type fuzzy controller and parameters adaptive method. *Fuzzy Sets and Systems* **78**, 23–35.

Ross T 2010 Fuzzy Logic with Engineering Applications 3rd edn. Wiley.

Rugh W and Shamma J 2000 Research on gain scheduling. Automatica 36, 1401–1425.

Rundqwist L 1991 Anti-reset windup for PID controllers In *Proc. 11th triennial world congress of the International Federation of Automatic Control, IFAC* (ed. Jaakso and Utkin), pp. 453–458. Pergamon Press.

Sala A, Guerra TM, and Babuška R 2005 Perspectives of fuzzy systems and control. *Fuzzy Sets and Systems* **156**, 432–444.

Self K 1990 Designing with fuzzy logic. *IEEE Spectrum* 27(11), 42–44 + 105.

Siler W and Ying H 1989 Fuzzy control theory: The linear case. Fuzzy Sets and Systems 33, 275–290.

Šiljak D 1968 Nonlinear Systems: The Parameter Analysis and Design. John Wiley & Sons.

Slotine JJE and Li W 1991 Applied Nonlinear Control. Prentice Hall.

Smith LC 1979 Fundamentals of control theory. Chemical Engineering 86(22), 11–39. (Deskbook issue).

Stoll RR 1979 Set Theory and Logic dover edn. Dover Publications, New York. (org 1963).

Sugeno M (ed.) 1985 Industrial applications of fuzzy control. North-Holland.

Sugeno M, Murofushi T, Mori T, Tatematsu T, and Tanaka J 1989 Fuzzy algorithmic control of a model car by oral instructions. *Fuzzy Sets and Systems* **32**(2), 207–219.

Takagi T and Sugeno M 1985 Fuzzy identification of systems and its applications to modeling and control. *IEEE Trans. Systems, Man & Cybernetics* **15**(1), 116–132.

Tanaka K, Sano M, and Suzuki K 1991 A new tuning method of fuzzy controllers *Proc. IFSA91*, pp. 207–210. IFSA. Tso SK and Fung YH 1997 Methodological development of fuzzy-logic controllers from multivariable linear control. *IEEE Trans. Systems, Man & Cybernetics* 27(3), 566–572.

von Altrock C 1995 Fuzzy Logic and Neurofuzzy Applications Explained. Prentice Hall.

von Altrock C 1996 Fuzzy Logic and Neurofuzzy Applications In Business And Finance. Prentice Hall PTR.

Wang LX 1997 A Course in Fuzzy Systems and Control international edn. Prentice Hall PTR.

Wenstøp F 1980 Quantitative analysis with linguistic values. Fuzzy Sets and Systems 4(2), 99–115.

Yamakawa T and Miki T 1986 The current mode fuzzy logic integrated circuits fabricated by the standard CMOS process. *IEEE Trans. Computers* **35**(2), 161–167.

Yamazaki T 1982 An improved algorithm for a self-organising controller and its experimental analysis PhD thesis Queen Mary College, London Dept. of Electrical and Electronic Engineering.

Yamazaki T and Mamdani EH 1982 On the performance of a rule-based self-organizing controller *Proc. IEEE Conf on Applications of Adaptive and Multivariable Control*, Hull.

Yasunobu S, Miyamoto S, and Ihara H 1983 Fuzzy control for automatic train operation system *Proc. Int. Congress on Control in Transportation Systems* IFAC/IFIP/IFORS, Baden-Baden.

Yazdi H 1997 Control and Supervision of Event-Driven Systems PhD thesis Technical University of Denmark Dept.

Ye Z 2007 Modeling, identification, design, and implementation of nonlinear automotive idle speed control systems: An overview. *IEEE Transactions on Systems, Man, and Cybernetics, Part C: Applications and Reviews.*

Zadeh L 1994 Soft computing and fuzzy logic. *IEEE Software* 11(6), 48–56.

Zadeh LA 1965 Fuzzy sets. Inf. and Control 8, 338-353.

Zadeh LA 1973 Outline of a new approach to the analysis of complex systems and decision processes. *IEEE Trans. Systems, Man & Cybernetics* 1, 28–44.

Zadeh LA 1975 The concept of a linguistic variable and its application to approximate reasoning. *Information Sciences* **8**, 43–80.

Zadeh LA 1984 Making computers think like people. *IEEE Spectrum* **21**, 26–32.

Zadeh LA 1988 Fuzzy logic. IEEE Computer 21(4), 83-93.

Ziegler J and Nichols N 1942 Optimum settings for automatic controllers. *Transactions of the American Society of Mechanical Engineers (ASME)* **64**, 759–768.

Ziegler J and Nichols N 1943 Process lags in automatic-control circuits. *Transactions of the American Society of Mechanical Engineers (ASME)* **65**, 433–444.

Zimmermann HJ 1993 Fuzzy set theory – and its applications 2nd edn. Kluwer, Boston.

Zimmermann HJ (ed.) 1999 Practical Applications of Fuzzy Technologies The Handbooks of Fuzzy Sets. Kluwer.