

CONTENTS

Preface - - - - -	9
Introduction - - - - -	11
PART I DISCRETE SYSTEMS OF THE VAN DER POL TYPE - - -	15
1. Methods of solution - - - - -	15
1.1 Basic considerations - - - - -	15
1.2 Methods of examining the equilibrium position stability and a method of determining the amplitude of the single-frequency self-excited vibration - - - - -	16
1.3 Analogue solution of steady vibrations - - - - -	24
2. Two-mass systems - - - - -	28
2.1 Survey of the systems analysed and their differential equations of motion	28
2.2 Investigation of equilibrium position stability by the method of boundary values - - - - -	31
2.3 Investigation of equilibrium position stability by the boundary curves method - - - - -	41
2.4 The dry friction effect—an approximate method of analysis - - - - -	46
2.5 Determination of amplitudes - - - - -	67
2.6 Solutions derived by analogue computational methods - - - - -	73
2.7 Systems subject to disturbance pulses; stability investigation - - - - -	86
2.8 Spring non-linearity and its effect on the system - - - - -	100
2.9 Summary - - - - -	102
3. Three-mass systems with a one-mass basic system - - - - -	106
3.1 Survey of the systems analysed and their equations of motion - - - - -	106
3.2 Boundary curves and optimum tuning - - - - -	108
3.3 The effect of the absorber tuning coefficient on the amplitude of self-excited vibration - - - - -	123
3.4 Solutions derived by analogue methods - - - - -	141
3.5 Summary of the results - - - - -	177
4. Systems with a multiple-mass basic system - - - - -	179
4.1 Survey of the systems and their equations of motion - - - - -	179
4.2 Boundary curves and the optimum tuning - - - - -	183

4.3	The effect of the absorber tuning coefficient on vibration amplitude	- - 191
4.4	Results of analogue solutions	- - - - - 208
4.5	Summary	- - - - - 214
PART II ROTOR SYSTEMS		- - - - - 217
5.	Basic assumptions and methods of solution	- - - - - 217
5.1	Basic considerations, description of self-exciting forces	- - - - - 217
5.2	Methods of investigating the stability boundary and determination of amplitudes of self-excited vibrations	- - - - - 220
6.	Symmetric rotor systems; the effect of resilient damped mountings	- - 222
6.1	Survey of the systems and their equations of motion	- - - - - 222
6.2	Stability boundary for Model X	- - - - - 227
6.3	Stability boundary for Model XI	- - - - - 230
7.	Asymmetric rotor systems; the effect of resilient damped mountings	- - 245
7.1	Survey of the systems and their equations of motion	- - - - - 245
7.2	Systems with a rigid rotor	- - - - - 251
7.3	Systems with elastic rotors	- - - - - 282
8.	A tuned absorber in rotor systems	- - - - - 290
8.1	Basic considerations and survey of the systems	- - - - - 290
8.2	Incorrect application of a tuned absorber	- - - - - 295
8.3	Tuned absorbers in symmetric systems	- - - - - 296
8.4	Tuned absorbers in asymmetric systems	- - - - - 306
9.	Seals and elastic mounting of the seal housings; their effect on the stability of rotor systems	- - - - - 315
9.1	Basic considerations	- - - - - 315
9.2	Analytic expression for seal forces	- - - - - 318
9.3	Analysis of a simple model	- - - - - 321
9.4	Elastic mounting of the seal housing	- - - - - 326
PART III VIBRATIONS OF SYSTEMS IN STREAMING FLUID		- - - 341
10.	Basic considerations	- - - - - 341
10.1	A survey of the systems analysed	- - - - - 341
10.2	The phase difference between the body displacement and the dynamic force of the flow; stability considerations	- - - - - 342
11.	Vibration of an elastic body induced by a cross flow in a straight channel	345
11.1	Vibration model based on the assumption of delayed body deflection	345
11.2	The effect of dry friction; stability investigation and domains of attraction	- - - - - 348
11.3	The effect of a tuned absorber	- - - - - 354
11.4	Vibration model based on the velocity equalization principle	- - - - - 356

11.5	The effect of additional dry friction	361
11.6	Stability investigation – domains of attraction	364
11.7	Comparison between the two basic models	368
12.	Elastic body in axial fluid stream; methods of modelling	369
12.1	A model comprising the channel	369
12.2	Systems with non-zero phase difference between the dynamic force and the body deflection	374
12.3	Analysis of Model XXV system including dry friction	375
12.4	Concluding remarks	382
13.	Model of a self-controlled system	383
13.1	Basic characteristics of the model	383
13.2	Methods of solution using an analogue computer; the effects of additional dry friction and external excitation force	388
13.3	The effect of a tuned absorber	396
13.4	The effect of an elastic damped mounting on stability	400
13.5	Summary of the results	403
14.	Conclusions	405
14.1	Generalized results of stability investigations	405
14.2	Application of the results to real systems	406
	References	412
	Index	417