

OBSAH

Emília BUBENÍKOVÁ, Alžbeta KANALÍKOVÁ, Marián HRUBOŠ1 Control of Mobile Robot Using Web Interface DOI: 10.22223/tr.2016-2/2013	
Karel FRYDRÝŠEK7 Simple Statically Indeterminate Truss (Linear, Nonlinear and Stochastic Approach) DOI: 10.22223/tr.2016-2/2014	
Stefan GRUSHKO, Zdenko BOBOVSKÝ21 Teleoperated Humanoid Robot DOI: 10.22223/tr.2016-2/2015	
Jaroslav HRICKO, Štefan HAVLÍK29 Stiffness Models of Novel Force/Displacement Sensors DOI: 10.22223/tr.2016-2/2016	
Marián HRUBOŠ, Dušan NEMEC, Vojtech ŠIMÁK, Jozef HRBČEK, Rastislav PIRNÍK37 Measurement of 3D Space Using a 2D Profilograph DOI: 10.22223/tr.2016-2/2017	
Vladislav OCHODEK, Stanislav RUSZ43 Residual Stresses Analysis Methodology During Cyclic Plastic Deformation Carbon Steel DOI: 10.22223/tr.2016-2/2018	
Jiří SUDER, Zdenko BOBOVSKÝ, Václav KRYS, Tomáš KOT49 Modifications of the Mobile Robotic System Crawler DOI: 10.22223/tr.2016-2/2019	
Ján VACHÁLEK, Oliver ROVNÝ, Rudolf PALENČÁR, Stanislav ĎURIŠ ...61 Measuring Distances Using the 3D Optical Device for the Needs of Mobile Robotics DOI: 10.22223/tr.2016-1/2020	
Karol VASILKO, Jozef PILC, Dana STANČEKOVÁ, Robert ČEP77 Development and Applications of a Free Cutting by Nonconventional Tools DOI: 10.22223/tr.2016-1/2021	