

# Contents

<b>Preface</b>	<b>ix</b>
<b>1 Introduction</b>	<b>1</b>
1.1 Hybrid Dynamical Systems . . . . .	1
1.2 Two Contrasting Examples of Discretely Controlled Continuous Variable Systems . . . . .	3
1.3 The Main Goal of This Book . . . . .	6
1.4 Organization of the Book . . . . .	7
1.5 List of Notations . . . . .	10
<b>2 Qualitative Analysis of Some Simple Hybrid Dynamical Systems</b>	<b>13</b>
2.1 Introduction . . . . .	13
2.2 Differential Automata and Their Trajectories . . . . .	15
2.3 Cyclic Linear Differential Automata . . . . .	17
2.4 Qualitative Analysis of Cyclic Linear Differential Automata . . . . .	23
2.5 Switched Server Systems with a Cyclic Switching Policy . .	27
2.6 Switched Server Systems with Several Limit Cycles . . . . .	30
2.7 Qualitative Analysis of Closed Switched Server Systems . .	33
2.8 Essentially Non-Periodic Dynamics of Switched Arrival Systems . . . . .	38

<b>3</b>	<b>General Theory of Multivalued Differential Automata</b>	<b>43</b>
3.1	Introduction . . . . .	43
3.2	Multivalued Differential Automata . . . . .	44
3.2.1	Basic assumptions and definitions . . . . .	45
3.2.2	Illustrative examples . . . . .	49
3.2.3	Invariant sets . . . . .	53
3.2.4	A partial classification of points in the phase space . . . . .	56
3.2.5	Deterministic and well-posed systems . . . . .	59
3.2.6	The skeleton and the backstepping mapping . . . . .	63
3.2.7	Asymptotically stable limit cycles . . . . .	64
3.3	Decomposition of Well-Posed Differential Automata . . . . .	67
3.4	Existence of Periodic Trajectories . . . . .	72
3.5	Proofs of the Theorems and Lemmas from Section 3.2 . . . . .	74
3.6	Proof of Theorem 3.2.26 . . . . .	85
3.7	Proofs of the Theorems from Sections 3.3 and 3.4 . . . . .	97
3.7.1	Proof of Theorem 3.4.3 . . . . .	102
<b>4</b>	<b>Two-Dimensional Hybrid Dynamical Systems</b>	<b>105</b>
4.1	Introduction . . . . .	105
4.2	An Analog of the Poincaré-Bendixon Theorem . . . . .	107
4.2.1	Basic assumptions . . . . .	107
4.2.2	A simple periodic dynamics . . . . .	115
4.2.3	A criterion for a simple periodic dynamics . . . . .	116
4.3	A Switched Arrival System with Three Buffers . . . . .	120
4.4	A Switched Server System with Three Buffers . . . . .	129
4.5	Proofs of the Statements from Section 4.2 . . . . .	155
4.5.1	Proofs of the lemmas from Section 4.2 . . . . .	155
4.5.2	Proof of Theorem 4.2.10 and the remarks following it . . . . .	166
<b>5</b>	<b>Limit Cycles in Hybrid Dynamical Systems with Constant Derivatives: General Theory</b>	<b>219</b>
5.1	Introduction . . . . .	219
5.2	Basic Assumptions and Definitions . . . . .	221
5.2.1	Multivalued differential automata with constant derivatives . . . . .	221
5.2.2	Key assumptions . . . . .	224
5.3	Criteria for Existence and Stability of Limit Cycles . . . . .	228
5.3.1	A complement concerning deterministic systems . . . . .	232
5.4	Proofs of the Lemmas from Section 5.2 . . . . .	236
5.5	Proofs of the Theorems and Lemmas from Section 5.3 . . . . .	241
5.6	Proofs of the Theorem and Lemmas from Subsection 5.3.1 . . . . .	261

<b>6</b>	<b>Limit Cycles in Hybrid Dynamical Systems with Constant Derivatives: Examples</b>	<b>269</b>
6.1	Introduction . . . . .	269
6.2	Qualitative Analysis of a Switched Server System . . . . .	272
6.2.1	Description of a switched server system . . . . .	272
6.2.2	A cyclic control policy . . . . .	273
6.2.3	The Clear-the-Largest-Buffer-Level Policy . . . . .	275
6.2.4	Structural stability of a switched server system . . . . .	277
6.3	A Switched Arrival System with Three Buffers . . . . .	282
6.4	Qualitative Analysis of Switched Single Server Flow Networks . . . . .	286
6.4.1	Single server flow networks . . . . .	286
6.4.2	A cyclic control policy . . . . .	289
6.4.3	A composed cyclic control policy . . . . .	296
6.4.4	A combined control policy . . . . .	298
<b>7</b>	<b>Globally Periodic Behavior of Switched Single Server Flow Networks</b>	<b>305</b>
7.1	Introduction . . . . .	305
7.2	Description of Switched Single Server Flow Networks . . . . .	306
7.3	Analysis of Switched Single Server Flow Networks . . . . .	311
<b>8</b>	<b>Regularizability of Switched Multiple Server Flow Networks</b>	<b>315</b>
8.1	Introduction . . . . .	315
8.2	Description of Switched Multiple Server Flow Networks . . . . .	316
8.3	Regularizable Switched Multiple Server Flow Networks . . . . .	321
8.4	Illustrative Example . . . . .	328
<b>9</b>	<b>Open Problems</b>	<b>331</b>
9.1	Introduction . . . . .	331
9.2	Switched Server Systems . . . . .	332
9.3	Essentially Nonperiodic Multidimensional Switched Arrival Systems . . . . .	333
9.4	Switched Server/Arrival Systems with Several Servers . . . . .	333
9.5	A Generalized Processor Sharing Model . . . . .	334
9.6	Stabilizability of Switched Multiple Server Flow Networks . . . . .	336
9.7	Chaotic Switched Flow Networks . . . . .	336
9.8	Existence and Global Stability of Limit Cycles in Nonlinear Differential Automata . . . . .	337
	<b>References</b>	<b>339</b>
	<b>Index</b>	<b>347</b>