Contents

1 Algebraic Preliminaries 1
1.1 Posets 1
1.2 Lattices 4
1.3 Equivalence Relations 7
1.4 Equivalence Kernel and Canonical Factorization 12
1.5 Application: Internal Model Principle 23
1.6 Notes 42
References 43

2 Linguistic Preliminaries 45
2.1 Languages 45
2.2 Nerode Equivalence and Right Congruence 46
2.3 Canonical Recognizers 48
2.4 Automata 57
2.5 Generators 60
2.6 Regular Expressions 66
2.7 Causal Output Mapping and Hierarchical Aggregation 69
2.8 Chains of Regular Languages 78
2.9 Notes 84
References 84

3 Supervision of Discrete-Event Systems: Basics 85
3.1 Introduction 85
3.2 Representation of Controlled Discrete-Event Systems 86
3.3 Synchronous Product, Shuffle, and Meet 89
3.4 Controllability and Supervision 100
3.5 Supremal Controllable Sublanguages and Optimal Supervision 104
3.6 Implementation of Supervisory Controls by Automata 109
3.7 Design of Supervisors Using *TCT* 114

3.8 Forced Events . . . 125
3.9 Supervisory Control for Reconfiguration . . . 130
3.10 Mutual Exclusion . . . 136
3.11 Supervisory Control by Relabeling . . . 138
3.12 Supervisor Reduction . . . 141
3.13 Notes . . . 142
References . . . 144

4 Decentralized and Distributed Supervision of Discrete-Event Systems . . . 147
4.1 Introduction . . . 147
4.2 Conjunction of Supervisors . . . 148
4.3 Naive Decentralized Supervision: Deadly Embrace . . . 150
4.4 Decentralized Supervision: Small Factory . . . 153
4.5 Decentralized Supervision: Big Factory . . . 154
4.6 Decentralized Supervision: Transfer Line . . . 157
4.7 Decentralized Supervision: AGVs in a Manufacturing Workcell . . . 163
4.8 Decentralized Supervision by Natural Projection . . . 184
4.9 Reasoning About Nonblocking . . . 190
4.10 Synchronization and Event Hiding . . . 196
4.11 Distributed Supervision by Supervisor Localization . . . 198
4.12 Notes . . . 201
References . . . 202

5 Hierarchical Supervision of Discrete-Event Systems . . . 205
5.1 Hierarchical Control Structure . . . 205
5.2 Two-Level Controlled Discrete-Event System . . . 207
5.3 High-Level Control Structure . . . 210
5.4 Command and Control . . . 215
5.5 Hierarchical Consistency . . . 220
5.6 Hierarchical Supervision of Transfer Line . . . 224
5.7 Hierarchical Supervision with Nonblocking . . . 228
5.8 Notes . . . 239
References . . . 254

6 Supervisory Control with Partial Observations . . . 257
6.1 Natural Projections and Normal Languages . . . 257
6.2 Observable and Relatively Observable Languages . . . 271
6.3 Feasible Supervisory Control . . . 280
6.4 Infimal Closed Observable Sublanguages . . . 295
6.5 Supervisory Control and Normality . . . 300
6.6 Control of a Guideway . . . 310
6.7 Nondeterminism, Quasi-congruences, and the Observer Property . . . 315

6.8 Efficient Coordination in Decentralized Control 331
6.9 Notes 337
References 337

7 State-Based Control of Discrete-Event Systems 339
7.1 Introduction 339
7.2 Predicates and State Subsets 339
7.3 Predicate Transformers 341
7.4 State Feedback and Controllability 343
7.5 Balanced State Feedback Controls and Modularity 347
7.6 Dynamic State Feedback Control 349
7.7 Notes 352
References 358

8 Supervision of Vector Discrete-Event Systems 361
8.1 Introduction 361
8.2 Vector Discrete-Event Systems 362
8.3 VDES Modeling 365
8.4 Linear Predicates 367
8.5 State Feedback and Controllability of VDES 368
8.6 Reachability and Loop-Freeness 371
8.7 Loop-Freeness and Optimal Control 375
8.8 Example: FACT#5 377
8.9 Memory and Dynamic State Feedback Control for VDES 381
8.10 Modular Dynamic State Feedback Control for VDES 382
8.11 Example: FACT#2 383
8.12 Modeling and Control of a Production Network 386
8.13 Representation of Optimal Control by a Control VDES 392
8.14 Notes 401
References 409

9 Supervisory Control of Timed Discrete-Event Systems 411
9.1 Introduction 411
9.2 Timed Discrete-Event Systems 412
9.3 Example 1 416
9.4 Example 2 418
9.5 Time Bounds as Specifications 419
9.6 Composition of TDES 420
9.7 Example 3 421
9.8 Controllability of TDES 421
9.9 Supremal Controllable Sublanguages and Optimal Supervision 428
9.10 Example 4: Endangered Pedestrian 430
9.11 Example 5: Timed Manufacturing Cell 433

9.12 Modular Supervision of Generalized TDES 439
9.13 Notes 443
References 443

Correction to: Supervisory Control of Discrete-Event Systems C1

Appendix A: Supervisory Control of a Mine Pump 445

Bibliography 461

Index 481