CONTENTS

NOTATION

Chapter 1 INTRODUCTION **1**

1.1 Finite Element Analysis **1**
1.2 Problem Classification, Modeling, and Discretization **3**
1.3 Interpolation. Elements, Nodes, and D.O.F. **5**
1.4 Example Applications. History of FEA **8**
1.5 Solving a Problem by FEA **11**
1.6 Learning and Using FEA **15**
Analytical Problems **17**

Chapter 2 ONE-DIMENSIONAL ELEMENTS AND COMPUTATIONAL PROCEDURES **19**

2.1 Introduction **19**
2.2 Bar Element **20**
2.3 Beam Element **24**
2.4 Bar and Beam Elements of Arbitrary Orientation **29**
2.5 Assembly of Elements **32**
2.6 Properties of Stiffness Matrices **36**
2.7 Boundary Conditions **40**
2.8 Exploiting Sparsity. Solving Equations **42**
2.9 Mechanical Loads. Stresses **46**
2.10 Thermal Loads. Stresses **52**
2.11 Structural Symmetry **54**
2.12 Review. Remarks Regarding Modeling **57**
2.13 An Application **59**
Analytical Problems **62**
Computational Problems **74**

Chapter 3 BASIC ELEMENTS **78**

3.1 Preliminaries **78**
3.2 Interpolation and Shape Functions **83**
3.3 Formulas for Element Matricies **88**
3.4 Linear Triangle (CST) **91**
3.5 Quadratic Triangle (LST) **95**
3.6 Bilinear Rectangle (Q4) **96**
3.7 Quadratic Rectangle (Q8, Q9) **100**
3.8 Rectangular Solid Elements **102**
3.9 Choice of Interpolation Functions **104**
3.10 Improved Triangles and Quadrilaterals **106**

3.11 Nodal Loads **111**
3.12 Stress Calculation **115**
3.13 Nature of a Finite Element Solution **118**
3.14 Example: A Simple Stress Concentration Problem **119**
3.15 An Application with High Stress Gradient **121**
Analytical Problems **124**
Computational Problems **132**

Chapter 4 FORMULATION TECHNIQUES: VARIATIONAL METHODS **136**

4.1 Introduction **136**
4.2 Principle of Stationary Potential Energy **137**
4.3 Problems Having Many D.O.F. **140**
4.4 Potential Energy of an Elastic Body **142**
4.5 The Rayleigh-Ritz Method **146**
4.6 Comments Regarding the Rayleigh-Ritz Method **149**
4.7 Strong Form and Weak Form **151**
4.8 Finite Element Form of the Rayleigh-Ritz Method **156**
4.9 Convergence of Finite Element Solutions **161**
4.10 Additional Formulations. Hybrid Elements **165**
Analytical Problems **171**

Chapter 5 FORMULATION TECHNIQUES: GALERKIN AND OTHER WEIGHTED RESIDUAL METHODS **179**

5.1 Galerkin Method **179**
5.2 Methods of Weighted Residuals (MWR) **182**
5.3 Galerkin Finite Element Method in One Dimension **186**
5.4 Integration by Parts **191**
5.5 Galerkin Finite Element Method in Two Dimensions **193**
5.6 A Mixed Formulation **195**
Analytical Problems **198**

Chapter 6 ISOPARAMETRIC ELEMENTS **202**

6.1 Introduction **202**
6.2 Bilinear Quadrilateral (Q4) **205**
6.3 Quadrature: [**k**] Obtained by Numerical Integration **209**
6.4 Quadratic Quadrilaterals (Q8, Q9) **213**
6.5 Hexahedral Isoparametric Elements **217**
6.6 Incompatible Modes. Nodeless D.O.F. **219**
6.7 Static Condensation **221**
6.8 Choices in Numerical Integration **223**
6.9 Load Considerations **227**
6.10 Stress Calculation **230**
6.11 Effect of Element Geometry **234**
6.12 Validity of Isoparametric Elements **237**
6.13 Patch Test **238**

6.14 A 2D Application **240**
6.15 A 3D Application **244**
Analytical Problems **247**
Computational Problems **255**

Chapter 7 ISOPARAMETRIC TRIANGLES AND TETRAHEDRA 259

7.1 Reference Coordinates. Shape Functions **259**
7.2 Element Characteristic Matrices **262**
7.3 Analytical Integration. Area and Volume Coordinates **264**
7.4 Numerical Integration **266**
Analytical Problems **268**

Chapter 8 COORDINATE TRANSFORMATION AND SELECTED ANALYSIS OPTIONS 271

8.1 Transformation: Introduction and Vector Forms **271**
8.2 Strain, Stress, and Material Property Transformation **273**
8.3 Transformation of the Characteristic Matrix **275**
8.4 Changing the Directions of Restraints **276**
8.5 Connecting Dissimilar Elements. Rigid Elements **278**
8.6 Higher Derivatives as Nodal D.O.F. **282**
8.7 Fracture Mechanics. Singularity Elements **283**
8.8 Elastic Foundations. Infinite Media **286**
8.9 Structural Modification. Reanalysis **292**
8.10 Tests of Element Quality **293**
Analytical Problems **295**
Computational Problems **299**

Chapter 9 ERROR, ERROR ESTIMATION, AND CONVERGENCE 300

9.1 Sources of Error **300**
9.2 Ill-Conditioning **302**
9.3 The Condition Number **306**
9.4 Diagonal Decay Test **308**
9.5 Residuals **309**
9.6 Discretization Error. Convergence Rate **310**
9.7 Multimesh Extrapolation **315**
9.8 Mesh Revision Methods **318**
9.9 Gradient (Stress) Recovery and Smoothing **320**
9.10 *A-Posteriori* Error Estimate **326**
9.11 Adaptive Meshing **329**
Analytical Problems **331**
Computational Problems **335**

Chapter 10 MODELING CONSIDERATIONS AND SOFTWARE USE 336

10.1 Introduction **336**
10.2 Physical Behavior Versus Element Behavior **337**
10.3 Element Shapes and Interconnection **340**

10.4 Test Cases and Pilot Studies **342**
10.5 Material Properties **344**
10.6 Loads and Reactions **347**
10.7 Connections in Structures **348**
10.8 Boundary Conditions **352**
10.9 Repetitive Symmetry **354**
10.10 Stress Concentrations. Submodels **356**
10.11 Substructures **358**
10.12 Planning an Analysis **360**
10.13 Common Mistakes **363**
10.14 Checking the Model **365**
10.15 Critique of Computed Results **366**
10.16 Design Optimization **369**
10.17 Software **370**
10.18 Concluding Remarks **371**
Analytical Problems **371**
Computational Problems **372**

Chapter 11 FINITE ELEMENTS IN STRUCTURAL DYNAMICS AND VIBRATIONS 373

11.1 Introduction **373**
11.2 Dynamic Equations. Mass and Damping Matrices **374**
11.3 Mass Matrices: Consistent, Diagonal, and Other **377**
11.4 Natural Frequencies and Modes **383**
11.5 Damping **388**
11.6 Reduction of the Number of D.O.F. **390**
11.7 Response History: Modal Methods **394**
11.8 Response History: Ritz Vectors **398**
11.9 Component Mode Synthesis (CMS) **400**
11.10 Harmonic Response **405**
11.11 Response History: Direct Integration Methods **407**
11.12 Explicit Direct Integration **409**
11.13 Implicit Direct Integration **416**
11.14 Direct Integration: Stability and Accuracy Analysis **421**
11.15 Analysis by Response Spectra **426**
11.16 Remarks. Modeling Considerations **429**
11.17 An Application: Vibration and Harmonic Response **436**
11.18 An Application: Response History **439**
Analytical Problems **444**
Computational Problems **451**

Chapter 12 HEAT TRANSFER AND SELECTED FLUID PROBLEMS 454

12.1 Heat Transfer: Introduction **454**
12.2 Finite Element Formulation **459**
12.3 Radiation. Nonlinear Heat Transfer Problems **462**
12.4 Transient Thermal Analysis **464**
12.5 Modeling Considerations. Remarks **467**

12.6 An Application **469**
12.7 Acoustic Frequencies and Modes **474**
12.8 Fluid-Structure Interaction **477**
12.9 Plane Incompressible Irrotational Flow **480**
Analytical Problems **482**
Computational Problems **486**

Chapter 13 CONSTRAINTS: PENALTY FORMS, LOCKING, AND CONSTRAINT COUNTING **489**

13.1 Explicit Constraints. Transformation Equations **489**
13.2 Lagrange Multipliers to Enforce Constraints **492**
13.3 Penalty Functions to Enforce Constraints **493**
13.4 Implicit Penalty Constraints and Locking **495**
13.5 Constraint Counting **499**
13.6 Remarks About Techniques for Incompressible Media **502**
Analytical Problems **504**

Chapter 14 SOLIDS OF REVOLUTION **508**

14.1 Introduction. Elasticity Relations for Axial Symmetry **508**
14.2 Axisymmetric Solid Elements **510**
14.3 An Application **512**
14.4 Loads Without Axial Symmetry: Introduction **516**
14.5 Loads Without Axial Symmetry: Some Details of FEA **521**
Analytical Problems **524**
Computational Problems **527**

Chapter 15 PLATE BENDING **530**

15.1 Introduction. Plate Behavior **530**
15.2 C^1 (Kirchhoff) Plate Elements **536**
15.3 C^0 (Mindlin) Plate Elements **542**
15.4 Mindlin Beam. More Devices for C^0 Plate Elements **547**
15.5 Boundary Conditions. Test Problems **551**
15.6 An Application **553**
Analytical Problems **556**
Computational Problems **559**

Chapter 16 SHELLS **561**

16.1 Introduction **561**
16.2 Circular Arches and Arch Elements **563**
16.3 Shells of Revolution **570**
16.4 General Shells: Three- and Four-Node Elements **574**
16.5 General Shells: Curved Isoparametric Elements **578**
16.6 Test Cases. Remarks **583**
16.7 An Axisymmetric Shell Application **586**
Analytical Problems **588**
Computational Problems **591**

Chapter 17 NONLINEARITY: AN INTRODUCTION 595

17.1 Nonlinear Problems **595**
17.2 Some Solution Methods **596**
17.3 Plasticity: Introduction **602**
17.4 Plasticity: General Formulation for Small Strains **606**
17.5 Plasticity: Formulation for Von Mises Theory **609**
17.6 Plasticity: Some Computational Procedures **612**
17.7 Nonlinear Dynamic Problems **616**
17.8 Problems of Gaps and Contact **619**
17.9 Geometric Nonlinearity **621**
17.10 Modeling Considerations. Remarks **626**
Analytical Problems **630**
Computational Problems **636**

Chapter 18 STRESS STIFFNESS AND BUCKLING 639

18.1 Introduction. Energy Considerations **639**
18.2 Bar and Beam Elements **642**
18.3 Plate Elements **645**
18.4 A General Formulation **646**
18.5 Calculation of Buckling Loads **648**
18.6 Remarks on Stress Stiffness and Its Uses **650**
18.7 Remarks and Examples **653**
Analytical Problems **656**
Computational Problems **661**

Appendix A MATRICES: SELECTED DEFINITIONS AND MANIPULATIONS 663

Appendix B SIMULTANEOUS ALGEBRAIC EQUATIONS 668

B.1 Overview **668**
B.2 Direct Solvers **668**
B.3 Iterative Solvers **671**

Appendix C EIGENVALUES AND EIGENVECTORS 675

C.1 Overview **675**
C.2 The Standard Eigenproblem **675**
C.3 The General Eigenproblem **676**
C.4 Solution Algorithms **679**

REFERENCES 682

INDEX 711